

General Relativity

Week 1

General relativity: Theory of gravity

Space & time jointly modeled by M^{3+1}

Equipped with Lorentzian metric g (M, g) : Lorentzian manifold

→ Causal structure

The geometry tells matter how to move, matter dictates how the spacetime is curved

$$\text{Ric} - \frac{1}{2} R \cdot g = 8\pi T$$

Aim of this course: Understand this eqn

- Half of the course geometry / half PDEs

Riemannian metric: Modeled on Euclidean inner product space

Lorentzian metric: Lorentzian inner product space

Def: Let V be an $n+1$ dim. vector space

A Lorentzian inner product is a map

$$m: V \times V \longrightarrow \mathbb{R}$$

which is:

- 1) bilinear
- 2) symmetric
- 3) non-degenerate, i.e. if $m(v, w) = 0 \quad \forall w \in V \Rightarrow v = 0$
- 4) Has signature $(1, n)$ (or $- + + \dots$)

i.e. maximum dimension of subspace $W \subseteq V$ with $m|_W$ positive definite is n .

~~Equivalently, n is the maximum dimension of subspace $W \subseteq V$ with $m|_W$ negative definite~~

Example: On $\mathbb{R}^2$: $m_1(v, w) = -v_0 w_0 + v_1 w_1$
 $m_2(v, w) = v_0 w_1 + w_0 v_1$

Given a basis $e_0, \dots, e_n$ of V :

The matrix $m_{\alpha\beta} = m(e_\alpha, e_\beta)$ is symmetric and invertible ↙ non-degenerate

and has 1 negative eigenvalue, n positive

If $X = X^\alpha e_\alpha$, $Y = Y^\beta e_\beta$

$m(X, Y) = m_{\alpha\beta} X^\alpha Y^\beta$ (Einstein summation)

Prop: There exists a basis $(e_0, e_1, \dots, e_n)$ in which

$m_{00} = -1$, $m_{ij} = \delta_{ij}$, $m_{0i} = 0$

(Convention: Greek letters $\alpha, \beta, \gamma, \dots = 0, 1, \dots, n$
 Latin letters $i, j, k, \dots = 1, \dots, n$)

So every (V, m) isometric to $(\mathbb{R}^{n,1}, \eta)$, $\eta = \begin{pmatrix} -1 & 0 & 0 \\ 0 & +1 & 0 \\ 0 & 0 & +1 \end{pmatrix}$

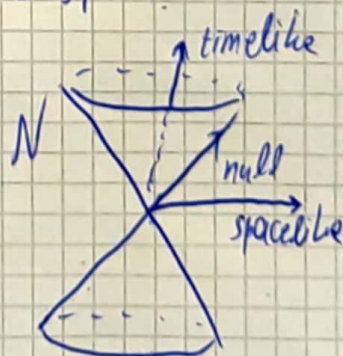
~~Definition~~

(Inner products of more general signature (p, q) : pseudo-Euclidean)

Def: Let (V, m) be a Lorentzian inner product space

A $v \in V \setminus \{0\}$ is

- timelike if $m(v, v) < 0$
 - null if $m(v, v) = 0$
 - spacelike if $m(v, v) > 0$
- } causal



$v > 0$: spacelike (convention)

Light cone $N = \{v \in V \setminus \{0\} : m(v,v) = 0\}$

Time cone $I = \{v \in V \setminus \{0\} : m(v,v) < 0\}$

← two components

In the exercises: If v is timelike and $w \perp v \Rightarrow w$ is spacelike

Prop: Gram-Schmidt process: Let v be a timelike vector. We can always find an orthonormal basis $e_0, e_1, \dots, e_n$ (i.e. $m(e_i, e_j) = \eta_{ij}$) with $e_0 = \rho \cdot v$, $\rho > 0$.

Def: A subspace $W \subseteq V$ is called:

- spacelike if $m|_W$ is positive definite
- null if $m|_W$ is degenerate
- timelike if $m|_W$ is Lorentzian

Most relevant for us: $\dim W = 1$ or $\text{codim } W = 1$

We will see in the exercises, if $v \in V \setminus \{0\}$:

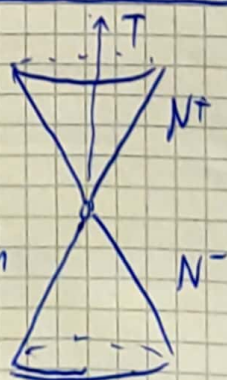
$$V^\perp = \begin{cases} \text{spacelike, if } v \text{ is timelike} \\ \text{null, if } v \text{ is null with } v \in V^\perp \\ \text{timelike, if } v \text{ is spacelike} \end{cases}$$



Null cone: N has two components. Pick one, call it future light cone N^+ .

Same as picking a timelike direction

T : $N^+ = \{v \in N : m(T, v) < 0\}$



Lemma: If v_1, v_2 are timelike vectors in the same time cone, then $m(v_1, v_2) < 0$

Proof: ~~Choose an orthonormal basis with $e_0, \dots, e_n$~~

Let T be the chosen timelike vector defining the future cone. Choose orthonormal basis $e_0, \dots, e_n$ so that $e_0 = \lambda T$, $\lambda > 0$.

Then v_1, v_2 in the same time cone as T

$$\Rightarrow v_1^0, v_2^0 < 0$$

$$\text{And: } v_1 \text{ timelike} \Rightarrow (v_1^0)^2 > \sum_{i=1}^n (v_1^i)^2$$

$$v_2 \quad " \quad \Rightarrow (v_2^0)^2 > \sum_{i=1}^n (v_2^i)^2$$

$$\begin{aligned} \text{So: } v_1^0 v_2^0 &= |v_1^0| |v_2^0| > \sqrt{\sum_i (v_1^i)^2} \sqrt{\sum_i (v_2^i)^2} \\ &\quad \uparrow \\ &\quad \text{both negative} \end{aligned}$$

$$\geq \sum_i v_1^i v_2^i \quad \text{Cauchy-Schwarz}$$

$$\Rightarrow \underbrace{-v_1^0 v_2^0 + \sum_{i=1}^n v_1^i v_2^i}_{m(v_1, v_2)} < 0$$

□

Def: $|v| := \sqrt{|m(v, v)|}$

Prop: Let v, w be timelike vectors

1) $|m(v, w)| \geq |v| |w|$, equality only if colinear
(reverse Cauchy-Schwarz inequality)

2) If in the same time cone:

$|v+w| \geq |v| + |w|$, equality only if colinear.

3) Def: Hyperbolic angle: (if in the same time cone):

$$m(v, w) = -|v| |w| \cosh \eta$$

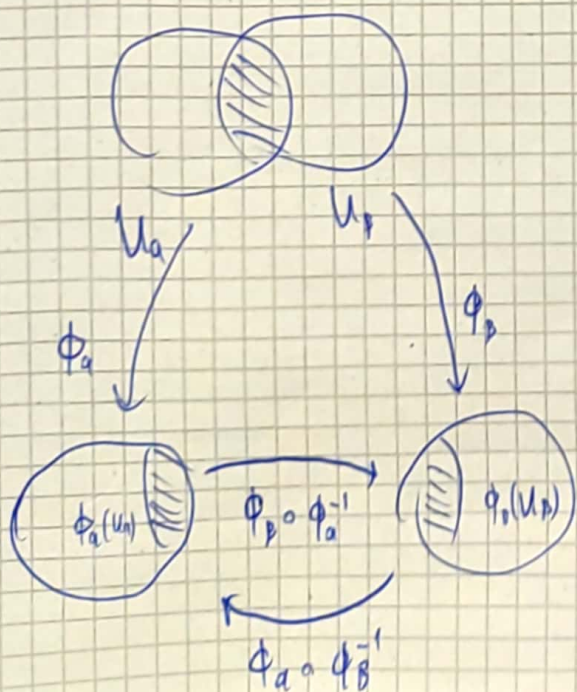
Smooth manifolds

Def: A smooth manifold M of dimension m is a Hausdorff, second countable top. space, together with open sets $\{U_\alpha\}_{\alpha \in A}$ and homeomorphisms $\phi_\alpha: U_\alpha \rightarrow \phi(U_\alpha) \subseteq \mathbb{R}^m$ s.t.

1) $M = \bigcup_\alpha U_\alpha$

2) If $U_\alpha \cap U_\beta \neq \emptyset$, then $\phi_\alpha \circ \phi_\beta^{-1}: \phi_\beta(U_\alpha \cap U_\beta) \rightarrow \phi_\alpha(U_\alpha \cap U_\beta)$ is a diffeomorphism of domains in $\mathbb{R}^m$

3) (U_α, ϕ_α) Maximal with properties 1 & 2



• (U_α, ϕ_α) : Coordinate chart

ϕ_α^{-1} : Parametrization

local coordinates $(x^1, \dots, x^m)$

- A collection $\{(U_\alpha, \phi_\alpha)\}_\alpha$ satisfying 1 & 2: Smooth atlas
- A maximal smooth atlas: Differentiable structure

From the above assumptions: $\exists$ partition of unity

- $\{\chi_\alpha\}$:
- $\text{Supp } \chi_\alpha \subseteq U_\alpha$ for some domain of a coordinate chart
 - $\text{Supp } \chi_\alpha \cap \text{Supp } \chi_\beta \neq \emptyset$ for finitely many β 's
 - $\sum_\alpha \chi_\alpha = 1$.

Smooth functions:

Def: Let $F: M \rightarrow N$ be a function. F is smooth at $p \in M$ (or C^k , etc) if its expression in local coordinates around p and $F(p)$ is smooth (or C^k , etc).

i.e. $\tilde{F} = \psi \circ F \circ \phi^{-1}$ is smooth for any chart (U, ϕ) on M around p and (V, ψ) on N around $F(p)$.

Note: Independent of coordinate charts

Tangent space - Cotangent space

Let M be a smooth manifold, $p \in M$.

Def: Tangent vector X_p at p : Linear map $X_p: C^\infty(M) \rightarrow \mathbb{R}$ such that (Leibniz rule)

$$X_p(f \cdot g) = X_p(f) \cdot g(p) + f(p) \cdot X_p(g).$$

$T_p M$: Set of tangent vectors at p

- Vector space, $\dim T_p M = \dim M$

If $(x^1, \dots, x^m)$ local coordinates: $\frac{\partial}{\partial x^i} \Big|_p$: Coordinate tangent vectors

- Form a basis of $T_p M$

→ indices up!

- Any tangent vector: $X = X^i \frac{\partial}{\partial x^i}$

(Smooth) vector field: a choice of a tangent vector X at every $p \in M$ s.t. the components X^i are smooth functions in any local coordinate chart.

Ex: If $\gamma: (-\epsilon, \epsilon) \rightarrow M$ is a smooth curve:

$$\dot{\gamma}(0) \in T_{\gamma(0)} M, \quad \dot{\gamma}(0)(f) := \frac{d}{dt}(f \circ \gamma) \Big|_{t=0}$$

In local coordinates: $\dot{\gamma}^i = \frac{dx^i}{dt}$

Cotangent space: $T_p^* M$: linear functionals $w: T_p M \rightarrow \mathbb{R}$

If $f \in C^\infty(M)$: $df_p(v_p) := v_p(f)$

Basis: $\{dx^i\}_{i=1}^m$

$$w = w_i dx^i$$

↑
Dual basis of $\left\{ \frac{\partial}{\partial x^i} \right\}_{i=1}^m$

$$dx^i \left(\frac{\partial}{\partial x^j} \right) = \delta_j^i$$

1-form: w_i smooth in any local coordinate chart.

Change of coordinate formula:

$$(x^1, \dots, x^n) \longrightarrow (y^1, \dots, y^n)$$

$$\boxed{\begin{aligned} dy^i &= \frac{\partial y^i}{\partial x^j} dx^j \\ \frac{\partial}{\partial y^i} &= \left[\frac{\partial y^{-1}}{\partial x} \right]_i^j \frac{\partial}{\partial x^j} = \frac{\partial x^j}{\partial y^i} \frac{\partial}{\partial x^j} \end{aligned}}$$

Lorentzian manifolds:

Def: Let M be a smooth manifold. A Lorentzian metric on M

1) an assignment g_p of a Lorentzian inner product on $T_p M$

$\forall p \in M$, s.t. $g_{ab} = g\left(\frac{\partial}{\partial x^a}, \frac{\partial}{\partial x^b}\right)$ is a smooth function in any local coordinate chart.

$$g(X, Y) = g_{ab} X^a Y^b$$

↑ symmetric (0,2) tensor field.

We will write $g = g_{ab} dx^a dx^b$

- A tangent vector $X_p \in T_p M$ is timelike / null / spacelike according to our previous definition
- A vector field $X \in \Gamma(M)$ is timelike / null / spacelike if it is " / " / " at every point
- A C^1 curve $\gamma: (a, b) \rightarrow M$ is timelike / null / spacelike if $\dot{\gamma}$ is
- A submanifold $S \subseteq M$ is similarly ... if $\forall p \in S, T_p S \subseteq T_p M$